

ON A TYPE OF ENTROPY OF DYNAMICAL SYSTEMS

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This contribution has three aims. First we compare the concept by D. Dumitrescu [2], [3] (see also [11]) with that by P. Malický and the author [5]. Secondly we present two counting formulas for the entropy [5]. Finally we present some remarks concerning the fuzzy entropy and especially we repeat the suggestion of P. Malický to define a very close but different invariant for fuzzy dynamical systems.

1. Measure preserving transformation and the entropy of a fuzzy partition

Following [2] and [3] we shall use the following definitions.

A family $\mathcal{F} \subset (0, 1)^X$ of fuzzy subsets of a set X is said to be a σ -algebra, if the following axioms are satisfied:

- (i) $1_X \in \mathcal{F}$.
- (ii) If $f, g \in \mathcal{F}$, then $f \cdot g \in \mathcal{F}$, $f - g \in \mathcal{F}$, where $f \cdot g(x) = f(x)g(x)$, $f - g(x) = \max(f(x) - g(x), 0)$.
- (iii) If $f_n \in \mathcal{F}$ ($n = 1, 2, \dots$), then $\bigcup_{n=1}^{\infty} f_n \in \mathcal{F}$, where $\bigcup_{n=1}^{\infty} f_n(x) = \min\left(\sum_{n=1}^{\infty} f_n(x), 1\right)$.

A function $m : \mathcal{F} \rightarrow \langle 0, \infty \rangle$ is called a fuzzy measure, if

- (i) $m(0_X) = 0$.
- (ii) $m\left(\bigcup_{n=1}^{\infty} f_n\right) = \sum_{n=1}^{\infty} m(f_n)$, whenever $f_n \in \mathcal{F}$ ($n = 1, 2, \dots$) and $\sum_{n=1}^{\infty} f_n \leq 1$.

A fuzzy partition is a finite collection $\mathcal{A} = \{f_1, \dots, f_n\}$ of members of \mathcal{F} such that $\sum_{i=1}^n f_i(x) = 1$ for all $x \in X$.

A fuzzy partition $\mathcal{A} = \{f_1, \dots, f_n\}$ is a refinement of a fuzzy partition $\mathcal{B} = \{g_1, \dots, g_m\}$, if there are disjoint sets $I(1), \dots, I(m) \subset \{1, \dots, n\}$ such that

$$g_i = \sum_{j \in I(i)} f_j,$$

for every $i = 1, \dots, m$. If \mathcal{A} is a refinement of \mathcal{B} , we write $\mathcal{A} \geq \mathcal{B}$.

A common refinement of two fuzzy partitions $\mathcal{A} = \{f_1, \dots, f_n\}$, $\mathcal{B} = \{g_1, \dots, g_m\}$ is the collection

$$\mathcal{A} \vee \mathcal{B} = \{f_i \cdot g_j : i = 1, \dots, n, j = 1, \dots, m\}.$$

(Of course, $\mathcal{A} \vee \mathcal{B} \geq \mathcal{A}$, $\mathcal{A} \vee \mathcal{B} \geq \mathcal{B}$.)

A transformation $T : X \rightarrow X$ is called measure preserving, if the following implication holds:

$$f \in \mathcal{F} \implies f \circ T \in \mathcal{F}, \quad m(f \circ T) = m(f).$$

If $\mathcal{A} = \{f_1, \dots, f_n\}$ is a fuzzy partition, then we define

$$T^{-1} = \{f_1 \circ T, \dots, f_n \circ T\}.$$

If $\mathcal{A} = \{f_1, \dots, f_n\}$ is a fuzzy partition, then its entropy $H(\mathcal{A})$ is defined by the formula

$$H(\mathcal{A}) = \sum_{i=1}^n \varphi(m(f_i)),$$

where $\varphi : (0, 1) \rightarrow \mathbb{R}$ is defined by $\varphi(x) = -x \log x$ ($x > 0$), $\varphi(0) = 0$.

Now if \mathcal{A} is a fuzzy partition, then we define

$$H_n(\mathcal{A}) = H(\mathcal{A} \vee T^{-1} \mathcal{A} \vee \dots \vee T^{-(n-1)} \mathcal{A}),$$

$$h(\mathcal{A}, T) = \lim_{n \rightarrow \infty} \frac{1}{n} H_n(\mathcal{A}),$$

$$h(T) = \sup\{h(\mathcal{A}, T); \mathcal{A} \text{ is a fuzzy partition}\}.$$

The previous definition is taken from [3]. Of course, the same definition has been presented in [5] in a more special case, where \mathcal{F} is a set of all measurable functions (with respect to a σ -algebra $\mathcal{S} \subset 2^X$) and $m(f) = \int f dP$, where $P : \mathcal{S} \rightarrow (0, 1)$ is a probability measure.

2. An alternative characterization of entropy

First we shall repeat some properties of the entropy $H(\mathcal{A})$ and the conditional entropy

$$H(\mathcal{A} | \mathcal{B}) = \sum_i \sum_j m(g_j) \varphi \left(\frac{m(f_i \cdot g_j)}{m(g_j)} \right),$$

where the sum is taken over all j for which $m(g_j) > 0$.

PROPOSITION 1. *If $\mathcal{A}, \mathcal{B}, \mathcal{C}$ are an arbitrary fuzzy partition, then*

- (i) $H(\mathcal{A} \vee \mathcal{B}) = H(\mathcal{B}) + H(\mathcal{A} | \mathcal{B})$,
- (ii) $\mathcal{A} \leq \mathcal{B} \implies H(\mathcal{A} | \mathcal{C}) \leq H(\mathcal{B} | \mathcal{C})$,
- (iii) $\mathcal{A} \leq \mathcal{B} \implies H(\mathcal{C} | \mathcal{A}) \geq H(\mathcal{C} | \mathcal{B})$.

THEOREM 1. $h(\mathcal{A}, T) = \lim_{n \rightarrow \infty} H \left(\mathcal{A} | \bigvee_{i=1}^n T^{-i} \mathcal{A} \right)$.

Proof. By Proposition 1 (i) we obtain

$$\begin{aligned} H \left(\bigvee_{i=0}^k T^{-i} \mathcal{A} \right) &= H \left(\mathcal{A} \vee T^{-1} \left(\bigvee_{i=0}^{k-1} T^{-i} \mathcal{A} \right) \right) = \\ &= H \left(T^{-1} \left(\bigvee_{i=0}^{k-1} T^{-i} \mathcal{A} \right) \right) + H \left(\mathcal{A} | \bigvee_{i=1}^k T^{-i} \mathcal{A} \right) = \\ &= H \left(\bigvee_{i=0}^{k-1} T^{-i} \mathcal{A} \right) + H \left(\mathcal{A} | \bigvee_{i=1}^k T^{-i} \mathcal{A} \right). \end{aligned}$$

Now by induction we obtain

$$(iv) \quad H \left(\bigvee_{i=0}^{n-1} T^{-i} \mathcal{A} \right) = H(\mathcal{A}) + \sum_{k=1}^{n-1} H \left(\mathcal{A} | \bigvee_{i=1}^k T^{-i} \mathcal{A} \right).$$

By (iii) we obtain that $H \left(\mathcal{A} | \bigvee_{i=1}^n T^{-i} \mathcal{A} \right)$ is decreasing, so that

$$\lim_{n \rightarrow \infty} H \left(\mathcal{A} | \bigvee_{i=1}^n T^{-i} \mathcal{A} \right)$$

exists. But then there exists also the limit of the Cesaro means

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n H \left(\mathcal{A} | \bigvee_{i=1}^k T^{-i} \mathcal{A} \right).$$

By (iv) we obtain

$$\begin{aligned} \lim_{n \rightarrow \infty} H \left(\mathcal{A} \mid \bigvee_{i=1}^n T^{-i} \mathcal{A} \right) &= \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n H \left(\mathcal{A} \mid \bigvee_{i=1}^k T^{-i} \mathcal{A} \right) = \\ &= \lim_{n \rightarrow \infty} \frac{1}{n} \left(H(\mathcal{A}) + \sum_{i=1}^{n-1} H \left(\mathcal{A} \mid \bigvee_{i=1}^k T^{-i} \mathcal{A} \right) \right) = \\ &= \lim_{n \rightarrow \infty} \frac{1}{n} H \left(\bigvee_{i=0}^{n-1} T^{-i} \mathcal{A} \right) = h(\mathcal{A}, T). \end{aligned}$$

□

Entropy and generators

The classical Kolmogorov-Sinaj theorem states that

$$h(T) = h(T, \mathcal{A}),$$

whenever \mathcal{A} is a generator of the dynamical system. A functional (= fuzzy) version of the generator theorem was presented in [5]. Here we want to present a generalization of the theorem in the general case (another modification is contained in [10]). The key is a representation theorem [1]:

PROPOSITION 2. Denote by \mathcal{S} the family $\{A \subset X; \mathcal{X}_A \in \mathcal{F}\}$ and define $\mu: \mathcal{S} \rightarrow \mathcal{R}$ by $\mu(A) = m(\mathcal{X}_A)$. Then every function $f \in \mathcal{F}$ is \mathcal{S} -measurable and

$$m(f) = \int_X f d\mu,$$

for every $f \in \mathcal{F}$.

Proof. [1], Theorem 4.1. □

According to Proposition 2 the Dumitrescu entropy $h(T)$ (with respect to X, \mathcal{F}, m, T) coincides with the Maličký and Riečan entropy $h_G(T)$ (with respect to X, \mathcal{S}, μ, T). Moreover, in [5] an arbitrary set G of functions is considered with $G \subset \mathcal{F}$ and then an invariant $h_G(T)$ is defined by

$$h_G(T) = \sup\{h(\mathcal{A}, T); \mathcal{A} \text{ is a finite partition, } \mathcal{A} \subset G\}.$$

Evidently $h_{\mathcal{F}}(T) = h(T)$.

Now as a corollary of a theorem of [5] we can obtain the following theorem for the fuzzy entropy.

THEOREM 2. If $\mathcal{A} = \{\mathcal{X}_{E_1}, \dots, \mathcal{X}_{E_n}\}$ is a fuzzy partition consisting of crisp sets generating the σ -algebra \mathcal{S} , then

$$h_G(T) \leq h(\mathcal{A}, T) + L_G,$$

where

$$L_G = \sup \left\{ m \left(\sum_{j=1}^n \varphi(g_j) \right); \{g_1, \dots, g_n\} \subset G \text{ is a fuzzy partition} \right\}.$$

Proof. By Proposition 2 there exists $\mu : \mathcal{S} \rightarrow \mathcal{R}$ such that

$$m(g) = \int_X g \, d\mu.$$

Now it is possible to use Theorem 1 from [5]:

$$h_G(T) \leq h(\mathcal{A}, T) + K_G,$$

where

$$K_G = \sup \left\{ \int \sum_{j=1}^n \varphi(g_j) \, d\mu; \{g_1, \dots, g_n\} \text{ is a fuzzy partition, } g_j \in G \right\}.$$

Evidently $K_G = L_G$. □

Concluding remarks

The generalization of the Kolmogorov–Sinaj invariant due to Dumitrescu, Maličký and the author has the following two advantages:

1. It can have a positive value also in some cases, when the Kolmogorov entropy is zero, hence the new invariant could better distinguish non-isomorphic dynamical systems.

2. It is applicable also for the case of fuzzy dynamical systems.

Of course, in many cases $h_G(T) = \infty$, e.g. if G contains all constant fuzzy sets.

3. As a solution of this problem P. Maličký in [5] suggested the following modification: instead of $H(\mathcal{A} \vee T^{-1}\mathcal{A} \vee T^{-(n-i)}\mathcal{A})$ to consider

$$H_n(\mathcal{A}) = \inf \{ H | \mathcal{C}; \mathcal{C} \geq \mathcal{A}, \mathcal{C} \geq T^{-1}\mathcal{A}, \dots, \mathcal{C} \geq T^{-n-1}\mathcal{A} \}.$$

4. Another solution of the preceding problem has been suggested by T. Hudetz in [4].

5. Another modification, we suggested in [5], is to consider a Markov operator $U : \mathcal{F} \rightarrow \mathcal{F}$ instead of the special case $U = U_T$ defined by $U_T(f) = f \circ T$.

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